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SLRS063-SEPTEMBER 2013

# DMOS DUAL ½-H-BRIDGE MOTOR DRIVERS

Check for Samples: DRV8816

# **FEATURES**

- Low ON-Resistance (0.83-Ω) Outputs
- Individual <sup>1</sup>/<sub>2</sub>-H bridge control
- Low-Power Sleep Mode
- 100% PWM Supported
- 8.0 38 V Operating Supply Voltage Range
- Thermally Enhanced Surface Mount Package
- Configurable Overcurrent Limit
- Protection Features
  - VBB Undervoltage Lockout (UVLO)
  - Charge Pump Undervoltage (CPUV)
  - Overcurrent Protection (OCP)
  - Short-to-Supply Protection (STS)
  - Short-to-Ground Protection (STG)
  - Overtemperature Warning (OTW)
  - Overtemperature Shutdown (OTS)
  - Fault Condition Indication Pin (nFAULT)

## **APPLICATIONS**

- Printers
- Industrial Automation

## DESCRIPTION

The DRV8816 provides a versatile power driver solution with two independent ½-H bridge drivers. The device can drive one brushed DC motor or one winding of a stepper motor, as well as other devices like solenoids. A simple INx/ENx interface allows easy interfacing to controller circuits.

The output stages use N-channel power MOSFET's configured as  $\frac{1}{2}$ -H-bridges. The DRV8816 is capable of peak output currents up to  $\pm 2.8$  A and operating voltages up to 38 V. An internal charge pump generates needed gate drive voltages.

A low-power sleep mode is provided which shuts down internal circuitry to achieve very low quiescent current draw. This sleep mode can be set using a dedicated nSLEEP pin.

Internal protection functions are provided for under voltage lockout, charge pump fault, overcurrent protection, short-to-supply protection, short-to-ground protection, overtemperature warning, and overtemperature shutdown. Fault conditions are indicated via an nFAULT pin

The DRV8816 is packaged in a 16 pin HTSSOP package with PowerPAD<sup>™</sup> (Eco-friendly: RoHS & no Sb/Br)



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

# **DRV8816**



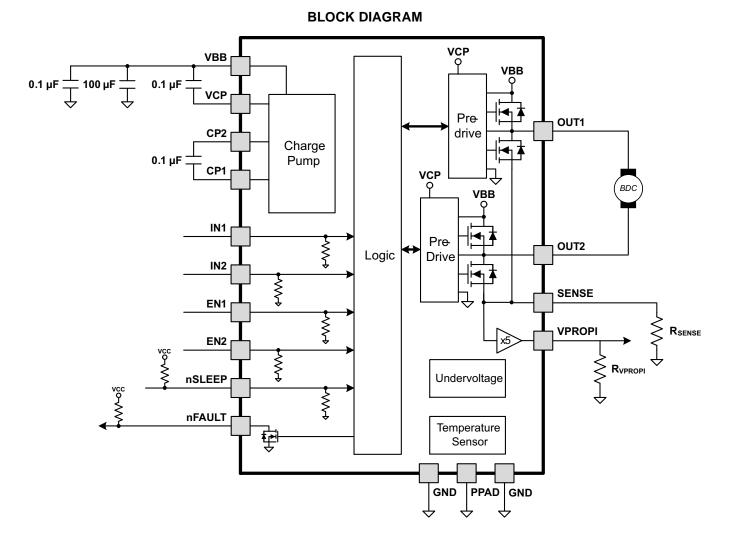
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This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.



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nFAULT 1 EN2 2 IN1 3	GND	16 15 14	in2 Vpropi VCP
GND 4 nSLEEP 5 EN1 6	verPAD.	13 12 11	GND CP2 CP1
OUT1 7 SENSE 8		10 9	OUT2 VBB

## **TERMINAL FUNCTIONS**

Name	Pin	Туре	Description	Comments
Power and	d Ground			
VBB	9	PWR	Power supply	Connect to motor supply voltage; bypass to GND with a 0.1 $\mu F$ plus a 100 $\mu F$ capacitor rated for VBB
GND	4, 13	PWR	Device ground	Must be connected to ground
VCP	14	0	Charge pump output	Connect a 16 V, 0.1 µF ceramic capacitor to VBB
CP1	11	-	Charge pump switching node	Connect a 0.1 $\mu F$ X7R capacitor rated for VBB between CP1 and CP2
CP2	12	-		
Control				
IN1	3	I	1/2-H bridge control	Logic high enables the high side ½-H bridge FET;
IN2	16			logic low enables the low side FET; internal pulldown
EN1	6	I	1/2-H bridge enable	Logic high enables ½-H bridge output; logic low
EN2	2			puts the FETs in HI-Z; internal pulldown
nSLEEP	5	I	Device sleep mode	Pull logic low to put device into a low-power sleep mode; internal pulldown
nFAULT	1	0	Fault indication pin	Pulled logic low with fault condition; open-drain output requires an external pullup
Output				
OUT1	7	0	1/2-H bridge output	
OUT2	10	0	1/2-H bridge output	
SENSE	8	0	H-bridge low-side connect	Connect directly to GND or through a sense resistor to set OCP
VPROPI				
VPROPI	15	0	Current-proportional output	

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## EXTERNAL COMPONENTS

Component	Pin 1	Pin 2	Recommended						
C <sub>VBB1</sub>	VBB	GND	0.1 µF capacitor rated for VBB						
C <sub>VBB1</sub> VBB GND			100 µF capacitor rated for VBB						
C <sub>VCP</sub>	VCP	VBB 16 V, 0.1 µF ceramic capacitor	16 V, 0.1 µF ceramic capacitor						
R <sub>nFAULT</sub>	VCC <sup>(1)</sup>	nFAULT	> 1 kΩ						
R <sub>SENSE</sub>	R <sub>SENSE</sub> SENSE GND		Optional low-side sense resistor connected to shunt						

(1) VCC is not a pin on the DRV8816, but a VCC supply voltage pullup is required for open-drain output nFAULT

## ABSOLUTE MAXIMUM RATINGS<sup>(1)</sup>

over operating free-air temperature range (unless otherwise noted)

		MIN	MAX	UNIT
VBB	Load supply voltage	-0.6	40	V
	Charge Pump Voltage (VCP, CP+)	-0.6	VBB + 7	V
	Charge pump negative switching pin range (CP-)	-0.6	VBB	V
VDD	Digital pin voltage range (IN1, IN2, EN1, EN2, nSLEEP, nFAULT)	-0.3	7	V
	VBB to OUTx	-0.6	40	V
	OUTx to SENSE	-0.6	40	V
V <sub>Sense</sub>	Sense voltage (SENSE)	-0.5	1.0	v
	H-bridge output current (OUT1, OUT2, SENSE)	0	2.8	А
	VPROPI pin voltage range (VPROPI)	-0.3	3.6	V
T <sub>A</sub>	Operating ambient temperature	-40	85	
Тj	Operating junction temperature	-40	190	°C
T <sub>stg</sub>	Storage temperature range	-40	125	]

(1) Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

#### **ELECTROSTATIC DISCHARGE PROTECTION**

	MIN	MAX	UNIT	
HBM on any other pin	2000		V	
Charge Device Model (CDM)	500			

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## THERMAL INFORMATION

		DRV8816	
	THERMAL METRIC <sup>(1)</sup>	PWP - HTSSOP	UNITS
		16 PINS	
$\theta_{JA}$	Junction-to-ambient thermal resistance <sup>(2)</sup>	43.9	
θ <sub>JCtop</sub>	Junction-to-case (top) thermal resistance <sup>(3)</sup>	30.8	
θ <sub>JB</sub>	Junction-to-board thermal resistance <sup>(4)</sup>	25.3	00444
ΨJT	Junction-to-top characterization parameter <sup>(5)</sup>	1.1	°C/W
Ψ <sub>JB</sub>	Junction-to-board characterization parameter <sup>(6)</sup>	25	
θ <sub>JCbot</sub>	Junction-to-case (bottom) thermal resistance <sup>(7)</sup>	5.6	

(1) For more information about traditional and new thermal metrics, see the *IC Package Thermal Metrics* application report, SPRA953.

(2) The junction-to-ambient thermal resistance under natural convection is obtained in a simulation on a JEDEC-standard, high-K board, as specified in JESD51-7, in an environment described in JESD51-2a.

(3) The junction-to-case (top) thermal resistance is obtained by simulating a cold plate test on the package top. No specific JEDECstandard test exists, but a close description can be found in the ANSI SEMI standard G30-88.

(4) The junction-to-board thermal resistance is obtained by simulating in an environment with a ring cold plate fixture to control the PCB temperature, as described in JESD51-8.

(5) The junction-to-top characterization parameter,  $\psi_{JT}$ , estimates the junction temperature of a device in a real system and is extracted from the simulation data for obtaining  $\theta_{JA}$ , using a procedure described in JESD51-2a (sections 6 and 7).

(6) The junction-to-board characterization parameter,  $\psi_{JB}$ , estimates the junction temperature of a device in a real system and is extracted from the simulation data for obtaining  $\theta_{JA}$ , using a procedure described in JESD51-2a (sections 6 and 7).

(7) The junction-to-case (bottom) thermal resistance is obtained by simulating a cold plate test on the exposed (power) pad. No specific JEDEC standard test exists, but a close description can be found in the ANSI SEMI standard G30-88.

# **RECOMMENDED OPERATING CONDITIONS**<sup>(1)</sup>

		MIN	MAX	UNIT
VBB	Power supply voltage range	8	38	V
VCC	Logic voltage		5.5	V
f <sub>PWM</sub>	Applied PWM signal (IN1 and IN2)		100	kHz
I <sub>OUT</sub>	H-bridge output current		2.8	А
T <sub>A</sub>	Ambient temperature	-40	85	°C

(1) Power dissipation and thermal limits must be observed.

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## **ELECTRICAL CHARACTERISTICS**

over recommended operating conditions (unless otherwise noted)

	PARAMETER	TEST	CONDITIONS	MIN	TYP	MAX	UNIT
POWER S	SUPPLIES (VBB)			·			
VBB	VBB operating voltage			8		38	V
	V/DD energing ourply ourrent	f <sub>PWM</sub> < 50 kHz			6		mA
I <sub>VBB</sub>	VBB operating supply current	Charge pump on, Outputs	disabled		3.2		mA
I <sub>VBBQ</sub>	VBB sleep-mode supply current	$nSLEEP = 0, T_J = 25^{\circ}C$				10	μA
CONTRO	L INPUTS (IN1, IN2, EN1, EN2, n	SLEEP)					
V <sub>IL</sub>	Input logic low voltage		V <sub>IN</sub> = 0.8 V	0		0.8	v
V <sub>IH</sub>	Input logic high voltage	IN1, IN2, EN1, EN2	V <sub>IN</sub> = 2.0 V	2		5.5	v
IIL	Input logic low current		V <sub>IN</sub> = 0.8 V	-20		+20	
I <sub>IH</sub>	Input logic high current	IN1, IN2, EN2	V <sub>IN</sub> = 2.0 V			20	μA
IIL	Input logic low current		V <sub>IN</sub> = 0.8 V		16	40	
IIH	Input logic high current	EN1	V <sub>IN</sub> = 2.0 V		40	100	μA
V <sub>IL</sub>	Input logic low voltage		V <sub>IN</sub> = 0.8 V			0.8	V
V <sub>IH</sub>	Input logic high voltage		V <sub>IN</sub> = 2.8 V	2.2			V
IIL	Input logic low current	nSLEEP	V <sub>IN</sub> = 0.8 V			10	
I <sub>IH</sub>	Input logic high current		V <sub>IN</sub> = 2.8 V		27	50	μA
R <sub>PD</sub>	Pulldown resistance				100		kΩ
SERIAL A	AND CONTROL OUTPUT (nFAUL	.T)		·			
V <sub>OL</sub>	Output logic low voltage	I <sub>sink</sub> = 1 mA				0.4	V
DMOS DF	RIVERS (OUT1, OUT2, SENSE)						
		Source driver, $I_{OUT} = -2.8$		0.48			
P		Source driver, $I_{OUT} = -2.8$		0.74	0.85		
R <sub>ds(ON)</sub>	Output ON resistance	Sink driver, I <sub>OUT</sub> = -2.8 A,		0.35		Ω	
		Sink driver, I <sub>OUT</sub> = -2.8 A,		0.52	0.7		
V <sub>TRP</sub>	SENSE trip voltage	R <sub>SENSE</sub> between SENSE	and GND		500		mV
	De de die de fermendere bene	Source diode, $I_f = -2.8 \text{ A}$				1.4	
V <sub>f</sub>	Body diode forward voltage	Sink diode, I <sub>f</sub> = 2.8 A			1.4	V	
	Deve eventing the last firm	INx, Change to source or		600			
t <sub>pd</sub>	Propagation delay time	INx, Change to source or	sink OFF		100		ns
t <sub>COD</sub>	Crossover delay				500		ns
DAGain	Differential amplifier gain	Sense = 0.1 V to 0.4 V			5		V/V
Protectio	n Circuits						
V <sub>UVLO</sub>	VBB undervoltage lockout	VBB rising			6.5	7.5	V
V <sub>CPUV</sub>	VCP undervoltage lockout <sup>(1)</sup>	VBB rising; CPUV recove	ry		12	13.8	V
I <sub>OCP</sub>	Overcurrent protection trip level			3			Α
t <sub>DEG</sub>	Overcurrent deglitch time				3.0		μs
t <sub>OCP</sub>	Overcurrent retry time						ms
T <sub>OTW</sub>	Thermal shutdown temperature	Die temperature T <sub>j</sub>			160		°C
T <sub>OTW HYS</sub>	Thermal shutdown hysteresis	Die temperature T <sub>j</sub>			15		°C
T <sub>OTS</sub>	Thermal shutdown hysteresis	Die temperature T <sub>j</sub>			175		°C
T <sub>OTS HYS</sub>	Thermal shutdown hysteresis	Die temperature T <sub>i</sub>			15		°C

(1) Whenever VCP is less than VM + 10 V, a CPUV event occurs. This fault will be asserted whenever VBB is below 12 V. Note that the H-bridges will remain enabled until VBB = V<sub>UVLO</sub> even through nFAULT is pulled low.



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# FUNCTIONAL DESCRIPTION

## **Power Supervisor**

Control input nSLEEP is used to minimize power consumption when the DRV8816 is not in use. This disables much of the internal circuitry, including the internal voltage rails and charge pump. nSLEEP is asserted low. A logic high on this input pin results in normal operation. When switching from low to high, the user should allow a 1-ms delay before applying PWM signals. This time is needed for the charge pump to stabilize.

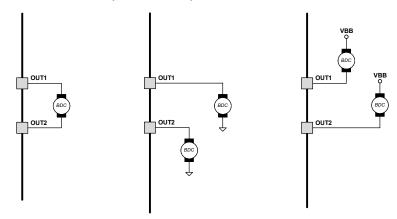
## Bridge Control

The DRV8816 is controlled using separate enable and input pins for each ½-H-bridge.

The following table shows the logic for the DRV8816:

ENx	INx	OUTx
0	Х	Z
1	0	L
1	1	Н

If a single DC motor is connected to the DRV8816, it is connected between the OUT1 and OUT2 pins as shown in the first image below. Two DC motors may also be connected to the DRV8816. In this mode, it is not possible to reverse the direction of the motors; they will turn only in one direction. The connections are shown below:



Motor operation for a single brushed DC motor is controlled as follows:

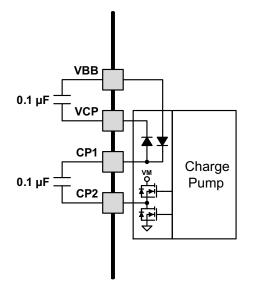
EN1	EN2	IN1	IN2	OUT1	OUT2	Operation
0	х	Х	Х	Z	See (1)	Off (coast)
Х	0	Х	Х	See (1)	Z	Off (coast)
1	1	0	0	L	L	Brake
1	1	0	1	L	н	Reverse
1	1	1	0	н	L	Forward
1	1	1	1	н	н	Brake

Motor operation for dual brushed DC motors is controlled as follows:

Motor connected	ENx	INx	OUTx	Operation
to GND	0	Х	Z	Off (coast)
	1	0	L	Brake
	1	1	Н	Forward
Motor connected	ENx	INx	OUTx	Operation
to VBB	0	Х	Z	Off (coast)
	1	0	L	Forward
	1	1	Н	Brake

## Charge Pump

The charge pump is used to generate a supply above VBB to drive the source-side DMOS gates. A  $0.1-\mu F$  ceramic monolithic capacitor should be connected between CP1 and CP2 for pumping purposes. A  $0.1-\mu F$  ceramic monolithic capacitor should be connected between VCP and VBB to act as a reservoir to run the high-side DMOS devices. The VCP voltage level is internally monitored and, in the case of a fault condition, the outputs of the device are disabled.



## SENSE

A low-value resistor can be placed between the SENSE pin and ground for current-sensing purposes. To minimize ground-trace IR drops in sensing the output current level, the current-sensing resistor should have an independent ground return to the star ground point. This trace should be as short as possible. For low-value sense resistors, the IR drops in the PCB can be significant, and should be taken into account.

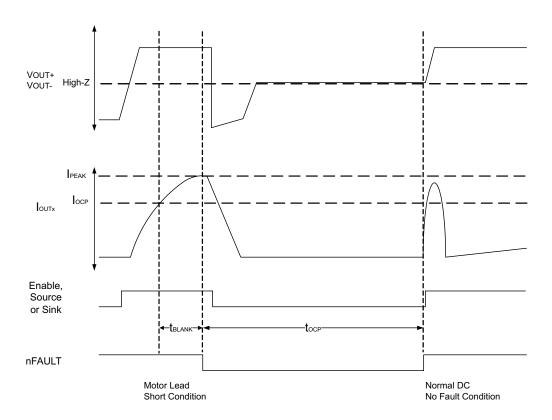
To set a manual overcurrent trip threshold, place a resistor between the SENSE pin and GND. When the SENSE pin rises above 500 mV, the H-bridge output is disabled (High-Z). The device will automatically retry with a period of  $t_{OCP}$ .

The overcurrent trip threshold can be calculated using  $I_{trip} = 500 \text{ mV/R}$ . The overcurrent trip level selected cannot be greater than  $I_{OCP}$ .

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## VPROPI

The VPROPI output is equal to approximately five times the voltage present on the SENSE pin. VPROPI is meaningful only if there is a resistor connected to the SENSE pin; If SENSE is connected to ground, VPROPI measures 0 V. Also note that during slow decay (brake), VPROPI will measure 0 V. VPROPI can output a maximum of 2.5 V, since at 500 mV on SENSE, the H-bridge is disabled.

## **Protection Circuits**

The DRV8816 is fully protected against VBB undervoltage, charge pump undervoltage, overcurrent, and overtemperature events.

## VBB UNDERVOLTAGE LOCKOUT (UVLO)

If at any time the voltage on the VBB pin falls below the undervoltage lockout threshold voltage, all FETs in the H-bridge will be disabled and the charge pump will be disabled. Operation will resume when VBB rises above the UVLO threshold. Note that nFAULT does not indicate a UVLO because the CPUV fault is always asserted below VBB = 12 V.

## VCP UNDERVOLTAGE LOCKOUT (CPUV)

During a CPUV event, the VCP voltage is measured to be below VCP + 10 V. If at any time the voltage on the VCP pin falls below the undervoltage lockout threshold voltage, the nFAULT pin will be driven low. The nFAULT pin will be released after operation has resumed. Note that this fault does not disable the output FETs and allows the device to continue operating. When VBB is below 12 V, this fault condition is always asserted and nFAULT is pulled low.

## **OVERCURRENT PROTECTION (OCP)**

The current flowing through the high-side and low-side drivers is monitored to ensure that the motor lead is not shorted to supply or ground. If a short is detected, all FETs in the H-bridge will be disabled, nFAULT is driven low, and a  $t_{OCP}$  fault timer is started. After this period,  $t_{OCP}$ , the device is then allowed to follow the input commands and another turn-on is attempted (nFAULT becomes high again during this attempt). If there is still a fault condition, the cycle repeats. If after  $t_{OCP}$  expires it is determined the short condition is not present, normal operation resumes and nFAULT is released.

### OVERTEMPERATURE WARNING (OTW)

If the die temperature increases past the thermal warning threshold the nFAULT pin will be driven low. Once the die temperature has fallen below the hysteresis level, the nFAULT pin will be released. If the die temperature continues to increase, the device will enter over temperature shutdown as described below.

#### **OVERTEMPERATURE SHUTDOWN (OTS)**

If the die temperature exceeds safe limits, all FETs in the H-bridge will be disabled and the charge pump will be shut down. Once the die temperature has fallen to a safe level operation will automatically resume.

#### THERMAL INFORMATION

#### **Thermal Protection**

If the die temperature exceeds approximately 150°C, the device will be disabled until the temperature drops to a safe level. Any tendency of the device to enter thermal shutdown is an indication of either excessive power dissipation, insufficient heatsinking, or too high an ambient temperature.

#### **Power Dissipation**

Power dissipation in the DRV8816 is dominated by the power dissipated in the output FET resistance, or  $R_{DS(ON)}$ . Average power dissipation can be roughly estimated by:

$$P_{TOT} = R_{D(SON)} \times (I_{OUT(RMS)})^2$$

(1)

where  $P_{TOT}$  is the total power dissipation,  $R_{D(SON)}$  is the resistance of the HS plus LS FETS, and  $I_{OUT(RMS)}$  is the RMS output current being applied to each winding.  $I_{OUT(RMS)}$  is equal to approximately 0.7× the full-scale output current setting.

The maximum amount of power that can be dissipated in the device is dependent on ambient temperature and heatsinking.

Note that R<sub>DS(ON)</sub> increases with temperature, so as the device heats, the power dissipation increases.

## PCB LAYOUT

#### Ground

A ground power plane should be located as close to DRV8816 as possible. The copper ground plane directly under the PowerPAD package makes a good location. This pad can then be connected to ground for this purpose.

#### Layout Considerations

The printed circuit board (PCB) should use a heavy ground plane. For optimum electrical and thermal performance, the DRV8816 must be soldered directly onto the board. On the underside of the DRV8816 is a PowerPAD package, which provides a path for enhanced thermal dissipation. The thermal pad should be soldered directly to an exposed surface on the PCB. Thermal vias are used to transfer heat to other layers of the PCB.

The load supply pin, VBB, should be decoupled with an electrolytic capacitor (typically 100  $\mu$ F) in parallel with a ceramic capacitor placed as close as possible to the device. The ceramic capacitors between VCP and VBB, connected to VREG, and between CP1 and CP2 should be as close to the pins of the device as possible, in order to minimize lead inductance.



25-Sep-2013

# **PACKAGING INFORMATION**

Orderable Device	Status	Package Type	•	Pins	Package	Eco Plan	Lead/Ball Finish	MSL Peak Temp	Op Temp (°C)	Device Marking	Samples
	(1)		Drawing		Qty	(2)		(3)		(4/5)	
DRV8816PWP	PREVIEW	HTSSOP	PWP	16	90	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	-40 to 85	DRV8816	
DRV8816PWPR	PREVIEW	HTSSOP	PWP	16	2000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	-40 to 85	DRV8816	

<sup>(1)</sup> The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.

**TBD:** The Pb-Free/Green conversion plan has not been defined.

**Pb-Free (RoHS):** TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes. **Pb-Free (RoHS Exempt):** This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between

the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

<sup>(3)</sup> MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

<sup>(4)</sup> There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

<sup>(5)</sup> Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

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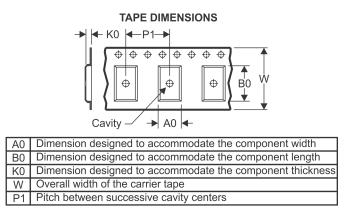
# PACKAGE MATERIALS INFORMATION

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## TAPE AND REEL INFORMATION





## QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nominal	
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Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
DRV8816PWPR	HTSSOP	PWP	16	2000	330.0	12.4	6.9	5.6	1.6	8.0	12.0	Q1

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# PACKAGE MATERIALS INFORMATION

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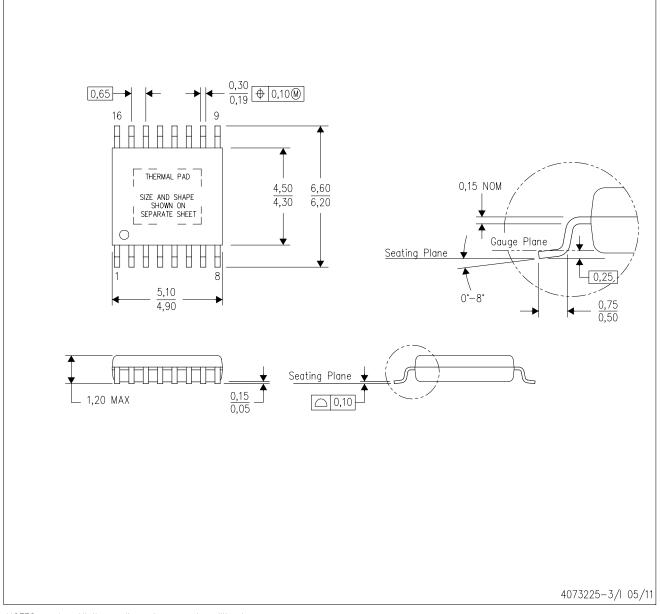


\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
DRV8816PWPR	HTSSOP	PWP	16	2000	367.0	367.0	35.0

PWP (R-PDSO-G16)

PowerPAD<sup>™</sup> PLASTIC SMALL OUTLINE

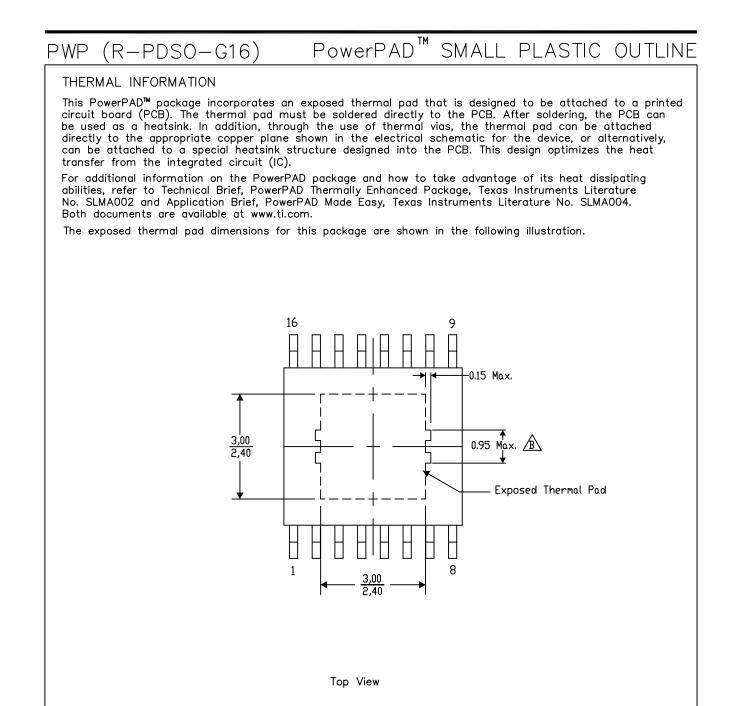


All linear dimensions are in millimeters. NOTES: Α.

- Β. This drawing is subject to change without notice.
- Body dimensions do not include mold flash or protrusions. Mold flash and protrusion shall not exceed 0.15 per side. C.
- This package is designed to be soldered to a thermal pad on the board. Refer to Technical Brief, PowerPad D. Thermally Enhanced Package, Texas Instruments Literature No. SLMA002 for information regarding recommended board layout. This document is available at www.ti.com <a href="http://www.ti.com">http://www.ti.com</a>. E. See the additional figure in the Product Data Sheet for details regarding the exposed thermal pad features and dimensions.
- E. Falls within JEDEC MO-153

PowerPAD is a trademark of Texas Instruments.





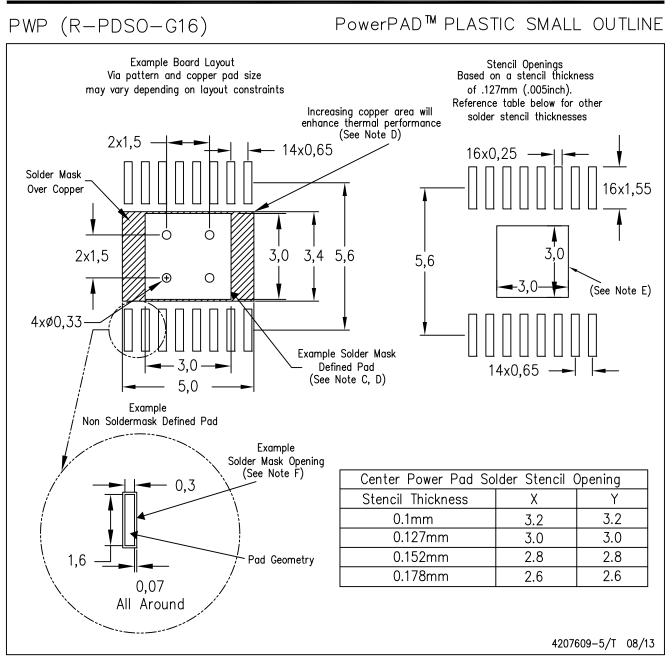


4206332-8/AG 08/13

NOTE: A. All linear dimensions are in millimeters A. All linear dimensions are in millimeters Exposed tie strap features may not be present.

PowerPAD is a trademark of Texas Instruments





NOTES:

A.

B. This drawing is subject to change without notice.

All linear dimensions are in millimeters.

- C. Customers should place a note on the circuit board fabrication drawing not to alter the center solder mask defined pad.
- D. This package is designed to be soldered to a thermal pad on the board. Refer to Technical Brief, PowerPad Thermally Enhanced Package, Texas Instruments Literature No. SLMA002, SLMA004, and also the Product Data Sheets for specific thermal information, via requirements, and recommended board layout. These documents are available at www.ti.com <http://www.ti.com>. Publication IPC-7351 is recommended for alternate designs.
- E. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Example stencil design based on a 50% volumetric metal load solder paste. Refer to IPC-7525 for other stencil recommendations.
- F. Customers should contact their board fabrication site for solder mask tolerances between and around signal pads.



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